

# L1-Controller user manual

(english)



Art.Nr. 9510

Art.Nr. 9510-F

Art.Nr. 9511

Art.Nr. 9511-F

12.01.2021

© PI 2021

# **index of contents**

## **L1-Controller**

### **1 Description**

### **2 Connecting options**

### **3 Control elements**

3.1 DIP-switch

3.2 display information

### **4 Configuration**

4.1 transmission protocol

4.2 Configuration

    4.2.1 Slave configuration

    4.2.2 Master configuration

        4.2.2.1 Configuration circulating list

        4.2.2.2 Configuration alarm list

        4.2.2.3 Configuration communication mode

        4.2.2.4 Configuration interrupt mode

        4.2.2.5 Save configuration data in flash memory

        4.2.2.6 Delete configuration data in flash memory

4.3 Configuration queries

    4.3.1 Configuration queries circulation list

    4.3.2 Configuration query alarm list

4.3.3 Configuration query communication mode

4.3.4 Configuration query slave configuration

## 4.4 Queries

4.4.1 State status query

4.4.1.1 PC -> L1-Controller

4.4.1.2 L1-Controller -> PC

4.4.2 Data request

4.4.2.1 PC -> L1-Controller

4.4.2.2 L1-Controller -> PC

## 4.5 transmit data

4.5.1 PC -> L1-Controller

# 5 Technical data

5.1 Pin assignment power supply

5.2 Pin assignment 9pole clamping socket

5.2.1 L1-BUS plug-in module (red)

5.2.2 TTY plug-in module

5.3 Pin assignment 9pole D-SUB socket

5.3.1 RS232 plug-in module

5.3.2 RS422 plug-in module

5.3.3 TTY plug-in module

# L1-Controller

## 1 Description

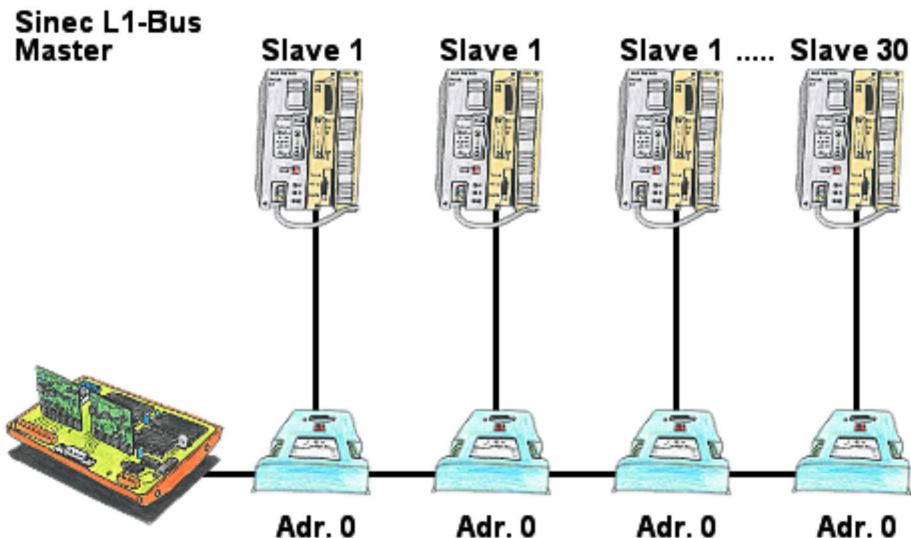
With the L1-BUS Controller, any computer can participate on the SINEC L1 bus from Siemens in master or slave. The only prerequisite is an asynchronous interface with RS-232 or RS-422 or TTY level.

Via a simple ASCII protocol the PC can exchange data with the L1-bus controller.

The entire L1-bus controller performs the functions autonomously even without computer performance.

## 2 Connecting options

Sinec-L1-Bus and no master (CP530)



## 3 Control elements

### 3.1 DIP-switch

8 7 6 5 4 3 2 1

| | | | \_| | \_|\_ 2 1

| | | | | OFF OFF = 19200 Baud

| | | | | OFF ON = 1200 Baud

| | | | | ON OFF = 2400 Baud

| | | | | ON ON = 9600 Baud

| | | | |

| | | | | \_ \_ \_ \_ ON = Checksum on

| | | | | OFF = Checksum off

| | | | | \_ \_ \_ \_ \_ \_ \_ \_ not used

| | | |

| | | \_ \_ \_ \_ \_ \_ \_ \_ ON = use timeout (500ms)

| | | OFF = no Timeout

| | | \_ \_ \_ \_ \_ \_ \_ \_ ON = Interactive mode ON

| | | OFF = Interactive mode OFF

| | \_ \_ \_ \_ \_ \_ \_ \_ ON = Echo ON

| | OFF = Echo OFF

## 3.2 display information

<b>display</b>	<b>description (state of L1Controllers)</b>
EE	RAM error, defective RAM module
21	STX get on the communication line (connection setup)
4D	L1-bus controller is configured as master
53	L1-bus controller is configured as slave
58	L1-bus controller is neither master nor slave, broadcasting ban! Define the circulation list (SME / KS)
00	Data is burned into the flash ROM (from V4.8ff, Flash)
08, 10, 18, 20, 28, 30, 38	Hardware interrupts should not appear

## 4 Configuration

## 4.1 transmission protocol

- Communication request with STX (02h)
  - send release with ENQ (05h)
  - end detection of the transmission ETX (03h)
  - acknowledgement positive ACK (06h)
  - acknowledgement negative NAK (21h)
  - no repetitions
  - Data format 8-bit, no-parity, 1 stop bit
  - Baud rate settable via DIP switch

- Checksum: 1 byte modulo 256 (over the entire frame)
- Structure of ZBE (status byte receive) and the ZBS (status byte transmit) as described in the manual of Siemens L1

### Example

No checksum (DIP switch 3 OFF)

Configuration query (from L1-Bus Controller)

### PC / terminal data direction L1-BUS-Controller

STX	=>	
	<=	ENQ
'K'	=>	
'M'	=>	
'U'	=>	
'?'	=>	
ETX	=>	
	<=	'K'
	<=	'M'
	<=	'U'
	<=	'!'
	<=	'0'
	<=	'1'
	<=	'0'
	<=	'1'
	<=	ETX

## 4.2 Configuration

### 4.2.1 Slave configuration

K = configuration

S = slave function

x = 1.ASCII for slave number (0 .. 3)

x = 2.ASCII for slave number (0 .. 9)

p = binary checksum

ETX

### 4.2.2 Master configuration

#### 4.2.2.1 Configuration circulating list

K = configuration

M = master function

U = circulating list

x = 1.ASCII length for circulating list (0 .. 9)

x = 2.ASCII length for circulating list (0 .. 9)

y = 1.ASCII for slave number (0 .. 3)

y = 2.ASCII for slave number (0 .. 9)

.

z = 1.ASCII for slave number (0 .. 3)

z = 2.ASCII for slave number (0 .. 9)

p = binary checksum

ETX

#### 4.2.2.2 Configuration alarm list

K = configuration

M = master function

A = alarm list

x = 1.ASCII length for alarm list (0 .. 9)

x = 2.ASCII length for alarm list (0 .. 9)

y = 1.ASCII for slave number (0 .. 3)

y = 2.ASCII for slave number (0 .. 9)

.

.

z = 1.ASCII for slave number (0 .. 3)

z = 2.ASCII for slave number (0 .. 9)

p = binary checksum

ETX

#### 4.2.2.3 Configuration communication mode

- PC must query as needed

K = configuration

C = kommunikation mode

P = polling mode

p = binary checksum

ETX

- PC gets sent a STX from the controller when changing the received data of the slaves and the controller expects an ENQ from the PC .

#### 4.2.2.4 Configuration interrupt mode

K = configuration

C = kommunikation mode

I = interrupt mode

p = binary checksum

ETX

#### 4.2.2.5 Save configuration data in flash memory

F = flash

! = save

p = binary checksum

ETX

possible only with flash version!

#### 4.2.2.6 Delete configuration data in flash memory

F = flash

C = delete

p = binary checksum

ETX

possible only with flash version!

## 4.3 Configuration queries

### 4.3.1 Configuration queries circulation list

K = configuration  
M = master function  
U = circulation list  
? = query  
p = checksum  
ETX

### 4.3.2 Configuration query alarm list

K = configuration  
M = master function  
A = alarmliste  
? = query  
p = checksum  
ETX

### 4.3.3 Configuration query kommunikation mode

K = configuration  
C = kommunikation mode  
? = query  
p = checksum  
ETX

### 4.3.4 Configuration query slave configuration

K = configuration  
S = slave function  
? = query  
p = checksum  
ETX

L1-Controller -> PC:  
response as under slave configuration or master configuration

## 4.4 Querys

### 4.4.1 State status query

#### 4.4.1.1 PC -> L1-Controller

Z = state status  
? = query  
x = 1.ASCII for slave number (0 .. 3)  
x = 2.ASCII for slave number (0 .. 9)  
p = binary checksum  
ETX

#### 4.4.1.2 L1-Controller -> PC

in slave number "00" ... "30"

Z = state status  
! = answer  
x = 1.ASCII for slave number (0 .. 3)  
x = 2.ASCII for slave number (0 .. 9)  
s = ZBS binary  
p = binary checksum  
ETX

in slave number "31"  
Z = state status  
! = answer  
x = 1.ASCII for slave number (3)  
x = 2.ASCII for slave number (1)  
y = 1.State-byte binary  
y = 2.State-byte binary  
y = 3.State-byte binary  
y = 4.State-byte binary  
p = binary checksum  
ETX

1. state-byte  
Bit 31 = reserve  
Bit 30 = change bit slave 30  
...  
Bit 24 = change bit slave 24

2. state-byte:  
Bit 23 = change bit slave 23  
...  
Bit 16 = change bit slave 16

3. state-byte:  
Bit 15 = change bit slave 15  
...  
Bit 8 = change bit slave 8

4. state-byte:  
Bit 7 = change bit slave 7  
...  
Bit 1 = change bit slave  
Bit 0 = change bit master

change bit:  
= 1 change since last request  
= 0 no change

#### 4.4.2 Data request

##### 4.4.2.1 PC -> L1-Controller

D = data  
? = request  
x = 1.ASCII number for slave (0...3)  
x = 2.ASCII number for slave (0...9)  
p = Prüfsumme binär  
ETX

#### 4.4.2.2 L1-Controller -> PC

D = datas  
! = answer  
x = 1.ASCII for slave number (0 .. 3)  
x = 2.ASCII for slave number (0 .. 9)  
y = 1.ASCII data length (0 .. 6)  
y = 2.ASCII data length (0 .. 9)  
s = ZBS binary  
z = 1. date binary  
. .  
z = n. date binary  
p = binary checksum  
ETX

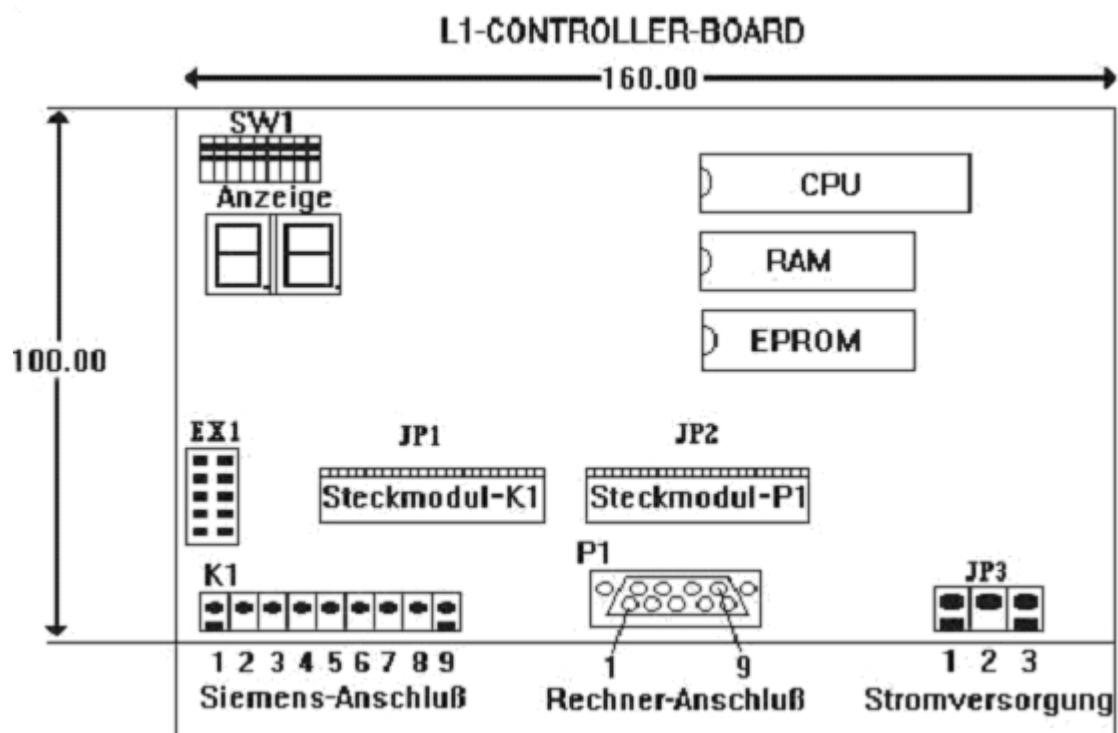
### 4.5 transmit data

#### 4.5.1 PC -> L1-Controller

D = datas  
! = send to L1-BUS Controller  
x = 1.ASCII for slave number (0 .. 3)  
x = 2.ASCII for slave number (0 .. 9)  
y = 1.ASCII data length (0 .. 6)  
y = 2.ASCII data length (0 .. 9)  
e = ZBE binary  
Strg A = 01h : AG RUN  
'A' = 41h : AG STOP  
z = 1. date binary  
. .  
z = n. date binary  
p = binary checksum  
ETX

## 5 Technical data

**Supply voltage:** 5V DC +/- 20%  
**Power consumption:** -  
**Display:** 2 x 7-segment display  
**Handling/Configuration:** DIP-Switch  
**others:**  
**Interfaces:** 1 x D-Sub-female 9pol for PC connection  
 3 x Weidmüller for 5V DC power supply  
 9 x Weidmüller for bus connection A and B  
**Operating temperature:** 0 - 55°C  
**Case:** plastic case  
**Dimensions:** 160 x 100 x 50 mm  
**Scope of delivery:**  
 L1-Controller



Plug-in module	Cable	Socket Type
L1-BUS	LC-485-BT-777	9pole clamping socket
TTY	LC-TTY-PG	9pole clamping socket
TTY	customized	9pole D-SUB socket
RS232	UN-ES-232-PC	9pole D-SUB socket
RS422	customized	9pole D-SUB socket

## 5.1 Pin assignment power supply

Pin number	Short form	Designation	Direction
1	VCC	+5V supply voltage	input
2	GND	mass	input
3	PE	earth connecting	input

## 5.2 Pin assignment 9pole clamping socket

### 5.2.1 L1-BUS plug-in module (red)

Pin number	Designation	on the BT-777 clamp
1	TxD +	1A
2	TxD -	2A
3	RxD +	3A
4	RxD -	4A
5	GND / mass	0A and 0B
6	TxD +	3B
7	TxD -	4B
8	RxD +	1B
9	RxD -	2B

#### Attention:

If the pins are 6/7/8/9 are not used, a bridge from 9 to 5 is necessary!  
If the pins are 1/2/3/4 are not used, a bridge from 4 to 9 is necessary!

### 5.2.2 TTY plug-in module

Pin number	Designation
1	TxD +
2	TxD -
3	RxD +
4	RxD -
5	I-TxD (20mA power source)
6	GND
7	I-RxD (20mA power source)
8	GND
9	+5V (protective resistance is over 100R)

#### Attention:

The inputs (RxD + and RxD-) and the outputs (TxD + and TxD-) are PASSIVE!

## 5.3 Pin assignment 9pole D-SUB socket

### 5.3.1 RS232 plug-in module

<b>Pin number</b>	<b>Short form</b>	<b>Designation</b>
1	shield	shield
2	RxD	receive data
3	TxD	transmit data
4	NC	not used
5	GND	mass

### 5.3.2 RS422 plug-in module

<b>Pin number.</b>	<b>Short form</b>	<b>Designation</b>
1	TxD +	transmit data +
2	TxD -	transmit data -
3	RxD +	receive data +
4	RxD -	receive data -

### 5.3.3 TTY plug-in module

<b>Pin number</b>	<b>Designation</b>
1	TxD +
2	TxD -
3	RxD +
4	RxD -
5	I-TxD (20mA power source)
6	GND
7	I-RxD (20mA power source)
8	GND
9	+5V (protective resistance is over 100R)

#### **Attention:**

The inputs (RxD + and RxD-) and the outputs (TxD + and TxD-) are PASSIVE!